A Predictive Model for the Daily Exchange Rate of the EUR/USD Using Markov Chain and Cointegration Techniques

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ABSTRACT

This paper adds to the literature of the exchange rates, some practical points which will be of great importance for financial markets and especially for the stock market. Firstly, the daily alternation of High and Low on the exchange rates of EUR/USD follows a uniform distribution and hence if someone bets on this alternation then he puts himself in a position of maximum uncertainty. Secondly, buying and selling always represent the care for the speculators seeking the right time to open or close their operations. Any decision deprived of necessary information of the exchange rate (market prices) and especially their volatility, leads to a high risk and the probability of failure of such a speculator is highly elevated. The four variables Open, High, Low and Close are stationary in first difference. Since the variables High and Low determine completely the daily extent of the exchange rate EUR/USD, one focused on their evolution taking into account the volatility resulting from an ARCH effect. For these two variables, one performs a measurement of risk using the family of ARCH models such as ARCH-M, EARCH symmetric and asymmetric and GJR-EARCH asymmetric. Thirdly, one presents an analysis of cointegration regression for the four systems of variables (High, Open), (Low, Open) and (High, Low, Open) and (High, Low, Open, Close). Therefore, the Open variable is very informative for those four systems because its value is known at the opening of the market, so it could be served as an endogenous and exogenous variable. Finally, one predicts prices and volatility of the high and Low using the (ECM) models associated to the two first systems and one shows that the ex-post forecasts reveal an excellent performance.

Keywords: exchange rates, stationary, Markov chain, ARCH, cointegration, forecasts

INTRODUCTION

After the Second World War, the USA was one of the first winners, and each country of this planet began to focus on the urban development and the economic and financial prosperity. The U.S. dollar became the most sought currency in the world. Actually, the U.S. economy recorded a GDP of USD 14 991.3 billion (Source World Bank 2011) in 2011, 21.42% of the world GDP evaluated at USD 69 981.9 billion at current prices and
18.54% of the world GDP (PPP) evaluated to 80,855.211 billion. A nation’s GDP at purchasing power parity (PPP) exchange rates is the sum value of all goods and services produced in the country valued at prices prevailing in the United States. The importance of the U.S. dollar is in attempting international comparison of exchange rates or GDP in current international dollars. Indeed, the current international dollar has now become a unit of reference in the world. The start of the euro as a rival currency to the USD has pushed all countries to focus on the exchange rate between the two currencies and many theoretical and practical studies have been done in order to try to give proper answers on the changes in the financial market where the stock market is its main axis. Actually, the European Union (EU) is an economic and political union of 27 member states where 17 countries have adopted the euro as a single currency. In 2011, the GDP (PPP) is 16441.916 billion, or 20.33% of the world GDP (PPP). This new state of the world economy has made the foreign exchange market between the euro and the dollar one of the most active ones in the world. In fact, the EUR/USD rate is the most financial instrument traded in the world. It is a leading indicator, daily followed by all economic and financial circles. This parity is calculated moment by moment, while the following four indicators of market movement are present: Open, High, Low and Close. The exchange rates EUR/USD have a great importance for the economy of a country, especially for its foreign trade. For example, suppose that the euro appreciates against the dollar, that is, the exchange rate EUR/USD increases from 1 € = $ 1.3020 to 1 € = $ 1.4020 a few months later, then the products exported by the United States to the countries of the Euro zone will be more competitive. Conversely, exports from the euro zone will have a higher price in USD and will be less competitive in the U.S. compared to local products. The price of EUR / USD move freely in a floating exchange rate, depending on the supply and demand in the interbank market. Allegret (2007) studies and outlines the main advantages and disadvantages of different exchange rate regimes and concludes that the intermediate regimes seem a better solution for emerging countries. Dunis et al. (2008) studied the forecasting and trading of the daily (EUR/USD) exchange rate using the European Central Bank (ECB) fixing series with only autoregressive terms as inputs. Bénassy-Quéré et al. (2009) propose an illustration for the euro/dollar exchange rate and suggest that the various approaches should be combined to provide useful benchmarks for exchange-rate policies.

In this research, the exchange rates of EUR / USD are available hour by hour, day by day, and month by month. One has two data files: (F1) of 65,328 hours in spot value, that is 2722 days are full, 24 hours per day, and another data file (F2) of size 2800 days (5 days per week without missing days, Monday to Friday) covering the period September 29, 2000 until November 16, 2011.

The choice of these two files is justified by this objective that consists in performing two types of analysis: first type, the F1 file was used to identify for each day, the time of

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1Purchasing power parity (PPP), Behavioral Equilibrium Exchange Rate (BEER) and Fundamental Equilibrium Exchange Rate (FEER).
2We selected only the full days with 24 hours of trade.
3The foreign exchange market, which is usually known as “forex” or “FX,” is the largest financial market in the world. The source of the data sets is from the Forex Time (FXTM) company which gives us access to the forex market 24 hours a day, 5 days a week, allowing us to trade over 60 currency pairs.
emergence of High and Low, and the distance time between them. Indeed, for market speculation, many speculators believe the almost deterministic alternating between High and Low. For example, in the first Friday of each month, the day of the meeting with the media, of Ben Shalom Bernanke, Chairman of the Federal Reserve, the central bank of the United States (Fed), and hence the realization of High or Low results of his declaration. One considers only the full days of 24 hours are the days in which the High and Low are theoretically equally likely to be observed. The important question that arises here is the following: which of the two variables is more likely to occur firstly in a day of 24 hours? This file will allow one, therefore, to search the times of High and Low through 24 hours of a full day, and to quantify this “alternation” between the High and Low. Another possible use of this file (F1) lies in the determination of the range of the time between the daily achievements of the High and Low. What is the law of this range? A question that certainly deserves a proper answer. To study the dual system for the High and the Low, one introduces a dummy variable of alternating High (DAH) with two integer values: 1 if the High occurs first in a day and 0 otherwise. It is clear that the two alternating systems are equivalent and hence one can just study the High system. To achieve this goal, one will use the technique of the Markov chain at first order. This work will allow one to estimate, in one hand, the two-state Markov model and in the other hand, to consider the long-term balance of probabilities states. It is clear that this system has two states consisting of the emerging of the High or not. Second type, it should be noted here that the file (F2) was introduced without missing data covering the period 01/01/2001 - 23/09/2011 (2800 days). Indeed, the time series contains 5 holidays whose values were estimated by the moving average smoothing technique. This series will be analyzed by the techniques of “family” ARCH and cointegration between the High and Low taking the variable Open as an exogenous variable because its value is known at the time of the opening of the market. It will be very interesting to introduce the opening value of the EUR/USD at the present time as an explanatory variable for dependent variable (High or Low). In fact this available information will have an impact to reduce the fluctuations in the Exchange Rate Market. This paper consists of an introduction, of three main areas and a conclusion. In the second section, one uses the technique of Markov chain at first order to carry out a study of the daily alternation of the variables high and low of the exchange rate EUR / USD. In the third section, a modeling volatility of the exchange rate will be developed using the conditional variance, a fundamental objective for the technical ARCH models. In the fourth section, a detailed analysis of the cointegration regression is performed by examining four systems choosing 2, 3 and 4 of the variables Open, Low, High and Close. Finally, one presents a conclusion based on the various results that are obtained earlier.

MARKOV ANALYSIS OF ALTERNATION HIGH SYSTEM

The discrete-time Markov chains at first order is a special case of all Markov stochastic processes \((X_t)_{t \in \mathbb{N}}\), I is called the state-space. The amount of information stored in the past at lag one influences its nearest future. Indeed, for a Markov chain, the information at a time \(t\) guides the observation at the next time. In other words, the Markov chains have no memory (Morris 1997) because the state of the system at the time \(t\) is the ”crossing bridge” that leads its state at time \(t+1\). For \(t \geq 0\), conditional probability on \(X_t, X_{t+1}\) has distribution \((p_{ij})_{t\in\mathbb{I}}\), and is independent of \(X_0, X_1, ..., X_{t-1}\) where \(X_0\) has a known distribution. Explicitly one can write:

\[
P(X_{t+1} = j | X_0 = i_0, ..., X_{t-1} = i_{t-1}, X_t = i) = p_{ij}
\]  

\[(R1)\]
The matrix $P = (p_{ij}, i,j \in \ell)$ is stochastic because every row $(p_{ij}, j \in \ell)$ is a distribution $(p_{ij} \geq 0$ and $\sum_{j=1}^{\ell} p_{ij} = 1)$. In most economic and social phenomena, one notes that the information progress in the time that moves forward and not backward (forward-looking), and hence the idea that time moves forward and not backward is quite current and familiar.

The discrete-time Markov chains is specified if one specifies the transition probabilities $p_{ij}$ between a state $i$ at the time $t$ and the state $j$ at the time $t+1$. If the state-space is finite and contains $(s)$ states, the matrix $P$ verifies:

$$P = (p_{ij})_{1 \leq i,j \leq s}$$

where all $p_{ij} \geq 0$ and for all $i,j$, $\sum_{i=1}^{s} p_{ij} = 1$ and $\sum_{i=1}^{s} p_{i} = 1$.

A discrete-time Markov chain will therefore be completely defined by the data of the transition matrix $P$ and by the state at the initial time. In addition, if for all coprime integers $n$ such that $P^{n+1} = P$. If after a number of iterations, $P^n$ tends to a limit matrix whose columns are all equal, which means that the distribution (proportion of each state) evolves into a single distribution which is a stationary distribution. The Markov chain is said to be stationary or homogeneous if the transition probability between state $i$ at time $t$ and the state $j$ at time $t+m$ depends only on the extent of the time (Papoulis, 1986) and so one obtains:

$$p^{(m)} = (p_{ij})_{1 \leq i,j \leq s} = P^m.$$  This means that the transition probability from one state to another in $m$ movements are simply obtained by the matrix $P$ to the power $m$. In general, one can write $p^m = p^u p^v$, $m = u + v$. In this case, the Markov chain is finite because the state-space contains two elements (1 and 0). The transition matrix $P$ is given by

$$P = \begin{pmatrix}
1-p & p \\
q & 1-q
\end{pmatrix}, \quad 0 < p < 1 \text{ and } 0 < q < 1$$

Where $p = P(X_{t+1} = 1|X_t = 0)$ and $q = P(X_{t+1} = 0|X_t = 1)$. The matrix $P$ is assumed to be regular, that is, there exists an integer $m$ such that the elements of the matrix $P^m$ are all positive. Let $V_t$ be the vector of state probabilities, that is, $V_t = (a_t, b_t)$. Obviously, one of the purposes of Markov analysis is to predict the future. Furthermore if one is in any period $t$, the state probabilities for period $t+1$ can be computed as follows:

$$V_{t+1} = V_t P \quad (R2)$$

Thus one can compute the equilibrium state probabilities. An equilibrium condition exists if the state probabilities do not change after a large number of periods. Thus, at the equilibrium, the state probabilities for a future period must be the same as the state probabilities for the current period (Render et al., 1994). This fact is the key to finding the equilibrium state probabilities. This relationship can be expressed as follows: $V = VP$
\[(a, b) = (a, b) \begin{pmatrix} 1-p & p \\ q & 1-q \end{pmatrix}\]  \hspace{1cm} (R3)

where \(a = P(X_t = 0)\) and \(b = P(X_t = 1)\). At equilibrium, the state probabilities must sum to 1. One can express this property as follows: \(a + b = 1\). Thus, the following 3 equations are obtained:

\[
\begin{align*}
  a &= a(1-p) + bq \\  b &= ap + b(1-q) \\  a + b &= 1
\end{align*}
\hspace{1cm} (E1) \hspace{1cm} (E2) \hspace{1cm} (E3)
\hspace{1cm} (R4)

Let one arbitrarily drop equation \((E1)\), and solve the following system:

\[
\begin{align*}
  b &= ap + b(1-q) \\  a + b &= 1
\end{align*}
\hspace{1cm} (E2) \hspace{1cm} (E3) \hspace{1cm} (R5)

One finds the equilibrium state probabilities:

\[
V = \frac{1}{p+q} (q, p) \hspace{1cm} (R6)
\]

and one can easily verify the following decomposition of the matrix of transition probabilities:

\[
P = \frac{1}{p+q} \begin{pmatrix} q & p \\ p & q \end{pmatrix} + \frac{(1-p-q)}{p+q} \begin{pmatrix} p & -p \\ -q & q \end{pmatrix} \hspace{1cm} (R7)
\]

One exploits the relation \(p^{n+1} = p^n p\) to write

\[
p^n = \frac{1}{p+q} \begin{pmatrix} q & p \\ p & q \end{pmatrix} + \frac{(1-p-q)^n}{p+q} \begin{pmatrix} p & -p \\ -q & q \end{pmatrix} \hspace{1cm} (R8)
\]

Using \(V_{n+1} = V_n p\), one obtains by recurrence:

\[V_1 = V_0 p, V_2 = V_1 p = V_0 p^2, \ldots, V_n = V_0 p^n\]

and consequently, the element of the vector of state probabilities at time \(t\) is obtained:

\[
\begin{align*}
  a_n &= \frac{1}{p+q} \left[ q + (1-p-q)^n (pa_0 - qb_0) \right] \\  b_n &= \frac{1}{p+q} \left[ p - (1-p-q)^n (pa_0 - qb_0) \right]
\end{align*}
\hspace{1cm} (R9)

Clearly, one has \(a_n + b_n = 1\) for all \(n\).
Since \(-1 < 1 - p - q < 1\), the two sequences \((a_n)_{n \geq 0}\) and \((b_n)_{n \geq 0}\) are convergent and they have as limit respectively \(\frac{q}{p+q}\) and \(\frac{p}{p+q}\). Both limits are independent of the initial values and have a sum equal to one\(^4\).

**Application:**

Consider the variables High and Low of the exchange rate EUR/USD. One knows that the trading day is 24 hours (from 0:00 to 0:00). The question that arises here is the following: which of two variables High and Low occurs before in the day? To do this, one looks at full days (a full day of 24 hours) for which their number is 2722. The alternation High system has the following estimate matrix of transition probabilities:

\[
P = \begin{pmatrix} 0.465 & 0.535 \\ 0.535 & 0.465 \end{pmatrix}
\]

\[
V_t = (0.5002, 0.4998)
\]

\[
V = \frac{1}{p + q}(p, q) = (0.5, 0.5)
\]

It appears that the alternating system of the variable High is in equilibrium, that is, the state probabilities for the current and future periods are the same. What does this result mean? In information theory (Escarpit, 1980), the uncertainty degree of the state of a system can be measured by entropy. This is a quantity defined by

\[
H(X) = -\sum_{i=1}^{s} p_i \log(p_i),
\]

\(p_i = P(X_t = i)\). In this theory, one uses logarithms to the base 2 and hence the entropy is measured in binary units. This agrees well with the system of representation of information in electronic calculators. It can be easily proved that the entropy of a system of a finite number of states, is maximal when all states are equally likely. It is sufficient to maximize \(H(X)\) under the constraint \(\sum_{i=1}^{s} p_i = 1\). Thus one seeks the extremum of the function

\[
F(p) = -\sum_{i=1}^{s} p_i \log(p_i) + \lambda \sum_{i=1}^{s} p_i,
\]

with \(\lambda\) is the Lagrange multiplier. The proof becomes very simple if one differentiates \(F(p)\) with respect to \(p_i\), \(i = 1, \ldots, s\) and then canceling these derivatives to obtain \(\log(p_i) = -\log(e) - \lambda\), \(i = 1, \ldots, s\).

The maximum corresponds to \(p_1 = \cdots = p_s = \frac{1}{s}\) and hence the maximum entropy of this system with two states is:

\[
H(X) = -\left[\frac{1}{2} \log \frac{1}{2} + \frac{1}{2} \log \frac{1}{2}\right] = 1 = \log(2)
\]

This result gives an important information about the daily realization of High exchange rate EUR/USD. The daily alternation of High and Low follows a uniform distribution, that is, the probability of observing firstly the High variable is equal to the probability of observing firstly the variable Low. As a result, the daily alternation of high and low is very random and it follows a uniform distribution and therefore the stock market speculators should not rely on this alternation. The maximum is reached when all the probabilities are equally likely.

\(^4\) For more information about the obtained recurrence relation, see Morris (1997).
UNIT ROOT TESTS

In times series analysis, it is important to test for whether the variables contain unit roots. It is widely recognized in the literature that a testing strategy is needed when testing for a unit root. Fuller (1976), Dickey and Fuller (1981), Perron (1988), Dolado et al. (1990), Enders (1995), and Ayat and Burridge (2000) propose such strategies:

\[ \Delta X_t = \alpha_0 + \alpha_1 t + \gamma X_{t-1} + \sum_{i=1}^{p-1} \varphi_i \Delta X_{t-i} + \varepsilon_t \quad (M) \]

where \( t \) is the time, and \( \Delta X_t \) is the variable \( X_t \) in first difference, \( p \) is the order AR model such that the associated residues behave like a white noise. Indeed, the non stationarity of a time series may be due to a linear trend (Trend stationary (TS)) or because of the variance which is related to the time and consequently the corresponding time series requires a difference at order \( d \) to become stationary (it is denoted \( I(d) \)), and in a such situation, the process is called (DS) (difference stationary). The Dickey-Fuller (ADF) procedure proposed by Dickey-Fuller is actually the most widely used. This procedure leads to decide about the type of non stationarity (TS or DS). For a variable \( X_t \), the (ADF) procedure distinguishes among three cases:

a) The equation (M) contains a constant and a trend.
b) The equation (M) contains a constant and without any trend.
c) The equation contains neither a constant nor a trend.

For cases (a), (b) and (c), the ADF procedure suggests respectively the test statistics called \( t_{FP} \), \( t_{FP} \) and \( t \). In practice, one estimates the equation (M) and one is interested in the \( t \) statistic \( t_{FP} \). The test statistic is the familiar \( t \) statistic but with special critical values employed to reflect its non normal (even asymptotically) distribution under the null of a unit root (Elder and Kennedy, 2001). In the following, one will use the ADF procedure using the RATS software (version 8.2) and one considers the file (F2) which covers data for the period 01/01/2001 - 23/09/2011 (2800 days). The order of the AR (p) model is properly selected to ensure the presence of residues that behave like a white noise. It seems that \( p = 100 \) is an appropriate value with this type of data. Indeed, 100 days are 4 months of the stock market, so this is a considerable past to predict the future. The results of unit root test shows that the first difference must be performed to ensure the stationarity of each of these variables. The results of the unit root tests are presented in Table (1). All variables are integrated at order one and this result is necessary to be able to use the two-step cointegration procedure suggested by Engle and Granger (1987).

MEASURE OF VOLATILITY IN THE EXCHANGE RATE EUR / USD

Instead of considering an \textit{ad hoc} variable \( X_t \) and \( I \) or perform a data transformation (log or other), Engle (1982) showed the possibility of simultaneously modeling the mean and variance of a time series. Engle methodology indicates that the conditional forecasts are more effective than the unconditional forecasts. Indeed, the unconditional prediction has an error prediction variance larger than that obtained in the case of conditional prediction. A simple strategy can be employed to predict the conditional variance as an AR (q) model. Assume that the variable is integrated of order \( d \) \( (X_t \sim I(d)) \), that is \( X_t = \Delta^d X_t \) stationary and it follows an AR (p) model where the \( \varepsilon \) are the residues. In the following, the models derived from the ARCH model, which are widely used in the financial market are briefly presented.
**TABLE 1**

**ADF Test for Unit Root of the Exchange Rate EUR/USD**  
**Period: from 01/01/2001 to 23/09/2011 (2800 Days)**

<table>
<thead>
<tr>
<th>ADF statistic s</th>
<th>First difference</th>
<th>Dependent variable $\Delta X_t$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$\tau$</td>
<td>$\tau_{\mu}$</td>
</tr>
<tr>
<td>p=100</td>
<td>-2.35</td>
<td>-2.02</td>
</tr>
<tr>
<td></td>
<td>-2.27</td>
<td>-2.08</td>
</tr>
<tr>
<td></td>
<td>-2.22</td>
<td>-2.08</td>
</tr>
<tr>
<td></td>
<td>-2.31</td>
<td>-2.11</td>
</tr>
</tbody>
</table>

**Critical values for Dickey-Fuller’s Unit Root at 5 % level**  
n=2800  $\tau_t = -3.41$  $\tau_{\mu} = -2.86$  and $\tau = -1.95$

**Conclusion**  
The variable $X_t$ is not stationary

<table>
<thead>
<tr>
<th>ADF statistics</th>
<th>Second difference</th>
<th>Dependent variable $\Delta^2 X_t$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$\tau$</td>
<td>$\tau_{\mu}$</td>
</tr>
<tr>
<td></td>
<td>-5.27</td>
<td>-5.20</td>
</tr>
<tr>
<td></td>
<td>-5.08</td>
<td>-4.99</td>
</tr>
<tr>
<td></td>
<td>-5.15</td>
<td>-5.06</td>
</tr>
<tr>
<td></td>
<td>-5.06</td>
<td>-4.97</td>
</tr>
</tbody>
</table>

**Conclusion**  
The variable $\Delta X_t$ is stationary: $X_t \sim I(1)$

**Overview of ARCH-type model:**

In this subsection, the 5 equations that follow the basic ARCH model are presented.

a) **ARCH(q) model**

The first ARCH model proposed by Engle (1982) is the one modeled by AR (q) the conditional variance of errors resulting from the model AR (p) of the variable in level $Y_t$:

$$E(e_{t+1}^2 | e_t) = \sigma_t^2 = h_t = a_0 + \sum_{i=1}^{q} a_i e_{t-i}^2$$

where $e_t$ is all the informations available in t, i.e. $e_t = \{e_{t+1}, \ldots, e_{t-1}, e_t\}$, the parameters $a_1, a_2, \ldots, a_q$ are nonnegative with $a_0 > 0$. The stationarity of the model ARCH(q) requires
the inequality $\sum_{i=1}^{q} a_i < 1$. The persistence of volatility is well modeled by specifying the conditional variance as a function of the square of past innovations.

**GARCH(p,q) model**: This is a generalization of the ARCH model suggested by Bollerslev (1986):

$$h_t = a_0 + \sum_{i=1}^{q} a_i e_{t-i}^2 + \sum_{j=1}^{p} \beta_j \sigma_{t-j}^2$$

where $a_0 > 0$, $0 \leq a_i < 1$ and $0 \leq \beta_j < 1$. It should be noted here that the stationarity of the model GARCH(p,q) requires the inequality $\sum_{i=1}^{q} a_i + \sum_{j=1}^{p} \beta_j < 1$.

**b) GARCH(p,q) in mean**

In the financial market, the speculators suggest that the average return would be higher in periods of high volatility. Engle et al. (1987) (ELR) proposed ARCH in Mean model as a way to integrate a function of the variance as a risk premium in the level model. The variable in question does not only depend on its past, but it also depends on the conditional variance which means unobservable predetermined variables (Droesbeke et al., 1994). The explanatory role of volatility can reduce the risk to assess the average level of the variable in question. Indeed, some factors are macroeconomic in nature and are correlated with the volatility (unobservable variable). Also they can help to predict best the variable under study. Therefore the calculable volatility value provided by GARCH models, acts as an explanatory variable for the variable in level:

$$Y_t = \varphi_0 + \sum_{i=1}^{q} \varphi_i Y_{t-i} + \theta \sqrt{h_t} + e_t$$

$$h_t = a_0 + \sum_{i=1}^{q} a_i e_{t-i}^2 + \sum_{j=1}^{p} \beta_j \sigma_{t-j}^2$$

**c) EGARCH(p,q)**

(Exponential General Autoregressive Conditional Heteroscedasticity) which was proposed by Nelson (1991): it allows a form of asymmetry which not only depends on the positive or negative sign of innovation, but also on the magnitude of the shock. Moreover, because of the logarithmic writing, the EGARCH model does not impose restrictions on the parameters. The general form of the EGARCH(p,q) model is:

$$\ln(h_t) = a_0 + \sum_{i=1}^{q} a_i g(Z_{t-i}) + \sum_{j=1}^{p} \beta_j \ln(h_{t-j})$$

$$g(Z_{t-i}) = \theta Z_{t-i} + \lambda (|Z_{t-i}| - E(|Z_{t-i}|))$$

where $Z_t = \frac{e_t}{\bar{e}_t}$. If we set $a_i = \theta a_i$, and $b_i = \lambda a_i$, $i = 1, \ldots, q$, then one obtains

$$\ln(h_t) = a_0 + \sum_{i=1}^{q} a_i Z_{t-i} + \sum_{i=1}^{q} b_i (|Z_{t-i}| - E(|Z_{t-i}|)) + \sum_{j=1}^{p} \beta_j \ln(h_{t-j})$$
where $Z_t = \frac{\varepsilon_t}{\sigma_t}$ is a homoscedastic white noise with zero mean and variance $\sigma_t^2$, $h_t$ is the conditional variance and $\sigma_t$, $\beta$, $\alpha_0$, $\alpha_1$, $\theta$ and $\lambda$ are real numbers. The parameter $\theta$ represents the effect of sign, and $\lambda$ is the effect of amplitude. The formulation of $g(Z_t)$ provides separate effects of volatility for $\theta$ and $\lambda$. Since the conditional variance $h_t$ is written in logarithm, then no restrictions need to be imposed on the parameters of the equation to ensure its positivity. The conditional variance $h_t$ shows the effects of sign corresponding to the terms $a_iZ_{t-i}$ and the effects of amplitude measured by $b_i((|Z_{t-i}| - E(|Z_{t-i}|))$, $i = 1, ..., q$. The parameter $\lambda$ indicates the presence of asymmetry due to the amplitude of the innovation. The effect of the magnitude of shock on the conditional variance depends on the sign of $\lambda$. If the parameter $\lambda$ is normalized to 1, then the properties of the EGARCH model can be summarized as follows: If $Z_t$ is positive then the function $g(Z_t)$ is linear in $Z_t$ with $(\theta+1)$ as slope. If $Z_t$ is negative then the $g(Z_t)$ is linear in $Z_t$ with $(\theta-1)$ as slope. If $\theta = 0$ then a great innovation increases the conditional variance if $(|Z_t| - E(|Z_t|)) > 0$ and decreases the conditional variance if $(|Z_t| - E(|Z_t|)) < 0$. The value of $E(|Z_t|)$ naturally depends on the governing distribution of $Z_t$. In RATS software, one considers the three usual distributions, which are the normal, the Student and the GED (Generalized Error Distribution) distributions. If $Z_t$ is a homoscedastic white noise $N (0,1)$, then $E(|Z_t|) = \frac{2}{\sqrt{\pi}}$. One notes that for the low degrees of freedom, the $t$ distribution is a leptokurtic distribution. Also, for GED distribution of parameter $\nu$, with $\nu$ strictly less than 2, the distribution has tails more thicker than those of a normal distribution (leptokurtic distribution). In the case where, if $\nu > 2$, then this distribution is platykurtic. If $\theta > 0$ (respectively $<0$), a positive shock on the conditional variance at time $t$ will result at time $t+1$ by an increase (respectively decrease) of the conditional variance in the case of volatility. To simplify the calculation, one will estimate a symmetric model EGARCH (1,1):

$$\ln(h_t) = a_0 + \alpha_1 \left[ \beta Z_{t-1} + \lambda ((|Z_{t-1}| - E(|Z_{t-1}|)) \right] + \beta_1 \ln(h_{t-1})(h_t) =$$

$$a_0 + \alpha_1 \left[ \theta \left( \frac{\varepsilon_{t-1}}{\sqrt{h_{t-1}}} \right) + \lambda \left( \frac{\varepsilon_{t-1}}{\sqrt{h_{t-1}}} - E \left( \frac{\varepsilon_{t-1}}{\sqrt{h_{t-1}}} \right) \right) \right]$$

or $\theta = 0$, and $\lambda$ normalized to 1, the symmetric model EARCH (1) has the equation:

$$\ln(h_t) = a_0 + \alpha_1 \left| \frac{\varepsilon_{t-1}}{\sqrt{h_{t-1}}} \right|$$

ARCH model with asymmetry: it is well known in the financial market that the distribution of prices is usually asymmetric, that is, you can see more downward than upward motion. In this application, one considers the asymmetric model EARCH (1)

$$\ln(h_t) = a_0 + \alpha_1 \left( \frac{\varepsilon_{t-1}}{\sqrt{h_{t-1}}} \right) + d_1 \frac{\varepsilon_{t-1}}{\sqrt{h_{t-1}}}$$

the asymmetric coefficient $d_1$ must be negative and significantly different from zero.

d) **GJR-EGARCH model**

The asymmetry can also be added to the standard GARCH model. Glosten et al. (1993) proposed the GJR-EGARCH model. Consider the simplest GJR-EGARCH(1,1) model:

$$h_t = c_0 + a_3 \varepsilon_{t-1}^3 + b_1 h_{t-1} + d_1 \varepsilon_{t-1}^3 I(\varepsilon_{t-1} < 0)$$
where $I(e_{t-1} < 0)$ denotes the indicator function defined by $I(e_{t-1} < 0) = 1$ if $e_{t-1} < 0$ and $I(e_{t-1} < 0) = 0$ otherwise. So if $e_{t-1} \geq 0$ then the term $e_{t-1}^2$ is multiplied by $\alpha_1$, and in the case where $e_{t-1} < 0$, then it is multiplied by $(\alpha_1 + d_2)$. Since the parameters are positive then the behavior is asymmetrical vis-à-vis shocks. This is the effect of "leverage" which means simply that the volatility is higher if a negative shock occurs (Bad News), and it is lower in the opposite case (Good News). In the following, the ARI (p)-GJR-EARCH (1) model will be estimated.

**Modeling the exchange rate EUR/USD**

Using the data file (F2), one will build the five models listed above for each of these variables Open, High, Low and Close. In Tables 2-3 (the variable $Y_t$ is the first difference for the variables High and Low respectively), the results of the estimation models ARI-ARCH are presented; an estimate made by the procedure STWISE available on RATS software (version 8.2, 2012). The $t$-statistic significance level for entering regression is fixed at 0.025. The ex-post forecasts were made step by step, on 373 days from September 24, 2011 until March 01, 2013. The forecast performance was measured by the criterion MAPE (Mean Absolute Percentage Error). For both High and Low variables, the MAPE value is 0.38% for the different proposed models. This interesting result probably reduces the risk when a decision to buy or sell is made by the speculators. The estimate ARCH(1) model is stationary because the coefficients of are respectively for the variables High and Low.

Finally, it is mentioned that the volatility does not explain the Low variable in level. Its coefficient is not significantly different from zero.

**ANALYSIS OF COINTEGRATION**

In econometrics, the impact of a variable on another variable can be instantaneous or time-lagged (Mourad & Harb, 2011). This is the multiplier effect at the short and long terms. The error correction model (ECM) is currently used by researchers in the finance and economic fields in which the presence of the static and dynamic relationships is of great interest for forecasting purposes. The popularity of the (ECM) model in applied econometric time series has increased since the representation theorem of Engle and Granger (1987): a linear combination of non-stationary variables integrated at the same order may be stationary. This relationship can be introduced into the model as an explanatory variable lagged at order one and the coefficient having a negative sign is interpreted as the return rate of the equilibrium state if a deviation between the variables has happened in the short term. Sargan (1964) used the (ECM) model to estimate the structural equations with autocorrelated residuals. According to Hylleberg and Mizon (1989) "the wording of the error correction provides an excellent structure in which it is possible to apply the information from the data and information available to economic theory". A specification and estimation study of the (ECM) model is made by Alogoskoufis and Smith (1995). Alexander (1999) performs a cointegration regression of the European, Asian and Far East (EAFE) Morgan Stanley Index, taken as dependent variable in log and the log price indices in local currencies of different countries. In Hong Kong, Oskooee and Chi-Wing (2002) examined the money demand at the long-term using the autoregressive distributed lag (ARDL) model on quarterly data. Hassler and Wolters (2006) published a very important paper performing a cointegration analysis in

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This index is widely used as a benchmark for the total international stock market.
the (ARDL) structure. They showed that the estimation of a cointegrated vector from an (ARDL) specification is equivalent to the (ECM) model. Using the procedure of Johansen (1988), Johansen and Juselius (1990), Johansen (1995) in studying the flow of the foreign direct investment, Mourad and Farhat (2007) found a long-run equilibrium relationship between the long-term developed countries and the rest of the world. A paper published by Shahbaz et al. (2008) suggested the existence of a strong relationship between stock market development and economic growth in Pakistan. A very recent paper (Mourad, 2012) deals with the private sector deposits in commercial banks in Lebanon. Using the procedure for cointegration described by Pesaran et al. (2001), the author shows that the residents' deposits in Lebanese pounds and the foreign currency deposits are linked by a low speed alignment to the long-run equilibrium when shocks occur in the short term. Using the Johansen procedure, Bangoura (2012) shows that there is a cointegration relationship between the variables of economic growth and financial development (GDP, domestic credit banking, domestic private sectors, and inflation) for the 11 CEDEAO countries and 7 UEMOA countries.

In the following, the two-step procedure of cointegration proposed by Engle and Granger (1987) will be used. Indeed, since there are a long size series in which the autoregressive models (AR) have a higher orders (p > 100) and since in these estimated models, there are many parameters that are not significantly different from zero, the use of the Johansen-Juselius procedure to estimate the vector of the error correction model (VECM) with all parameters will lead to highly charged models with a mixing of significant and insignificant parameters. On the other hand, in these systems, especially the first two systems, the Open variable is observed at time (T + 1), where T is the present time. Indeed, it is the time of opening market at midnight in the Middle East countries and consequently, the value of the Open variable will participate better in the forecasting of the variables High and Low. For stock market speculators, the forecast for high and low is very important because any decision concerning buying or selling depends on it. In the following, one will discuss the four following systems:

System 1: It involves the two variables Open and High.
System 2: It involves the two variables Open and Low.
System 3: It involves the three variables Open, Low and High.
System 4: It is concerned with the four variables Open, Low, Close and High.

The number of parameters m in any long-term equilibrium relationship of the system (i), i = 1, 2, 3, 4 are respectively 2, 2, 3 and 4. Next, the first 2800 observations of the data file (F2) are used to estimate the four systems, then one performs a calculation of ex-post forecasts for the 373 days starting from September 24, 2011 until March 01, 2013.

To test the static cointegration between the variables of a system, the two-step procedure proposed by Engle and Granger (1987) will be used:

**Step 1:** One identifies the order of integration (d) for each variable.

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7A system is a model that explores the dynamic relationship between two or more variables.
<table>
<thead>
<tr>
<th>Models</th>
<th>Equation</th>
<th>MAPE</th>
</tr>
</thead>
<tbody>
<tr>
<td>ARI(81)-ARCH(1)</td>
<td>$Y_t = 0.123 Y_{t-1} + 0.039 Y_{t-7} + 0.043 Y_{t-63} - 0.036 Y_{t-81}$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>$h_t = 0.0000468 + 0.1425 e_{t-1}^2$</td>
<td>0.38%</td>
</tr>
<tr>
<td>ARI(81)-ARCH(1).M</td>
<td>$Y_t = 0.1224 Y_{t-1} + 0.0388 Y_{t-7} + 0.0425 Y_{t-63} - 0.0362 Y_{t-81} + 0.0303 \sqrt{h_t}$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>$h_t = 0.0000466 + 0.1466 e_{t-1}^2$</td>
<td>0.38%</td>
</tr>
<tr>
<td>ARI(81)-EARCH(1)</td>
<td>$Y_t = 0.123 Y_{t-1} + 0.0444 Y_{t-7} + 0.052 Y_{t-63} - 0.030 Y_{t-81} + 0.037 \sqrt{h_t}$</td>
<td></td>
</tr>
<tr>
<td>Without asymmetry</td>
<td>$ln(h_t) = -10.033 + 0.27 \frac{e_{t-1}}{h_{t-1}}$</td>
<td>0.38%</td>
</tr>
<tr>
<td></td>
<td>$-292.26$</td>
<td>(8.63)</td>
</tr>
<tr>
<td>ARI(81)-EARCH(1) with asymmetry</td>
<td>$Y_t = 0.1271 Y_{t-1} + 0.0453 Y_{t-7} + 0.0550 Y_{t-63} - 0.0247 Y_{t-81} + 0.0315 \sqrt{h_t}$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>$ln(h_t) = -10.053 + 0.2919 \frac{e_{t-1}}{h_{t-1}} - 0.0705 e_{t-1}$</td>
<td>0.38%</td>
</tr>
<tr>
<td></td>
<td>$-294.43$</td>
<td>(9.1)</td>
</tr>
<tr>
<td>ARI(81)-GJR-ARCH(1) with asymmetry</td>
<td>$Y_t = 0.1295 Y_{t-1} + 0.0415 Y_{t-7} + 0.0476 Y_{t-63} - 0.0296 Y_{t-81}$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>$h_t = 0.0000458 + 0.1228 e_{t-1}^2 + 0.0981 e_{t-1}^2$ if $e_{t-1} &lt; 0$</td>
<td>0.38%</td>
</tr>
</tbody>
</table>

**TABLE 2**

Estimated Models for the Variable High
### TABLE 3

Estimated Models for the Variable Low

<table>
<thead>
<tr>
<th>Models</th>
<th>Estimated Equation</th>
<th>MAPE</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>ARI(100)-ARCH(1)</strong></td>
<td>$Y_t = 0.160 Y_{t-1} + 0.039 Y_{t-15} + 0.042 Y_{t-50} + 0.042 Y_{t-65} - 0.055 Y_{t-66} + 0.05 Y_{t-77} - 0.069 Y_{t-86} + 0.064 Y_{t-87}$</td>
<td>0.38 %</td>
</tr>
<tr>
<td></td>
<td>$-0.034 Y_{t-95} + 0.063 Y_{t-100}$ and $h_t$</td>
<td>$= 0.000045 + 0.1028 e_{t-1}^2$</td>
</tr>
<tr>
<td></td>
<td>$h_t = 0.000045 + 0.1028 e_{t-1}^2$</td>
<td>$= 0.000045 + 0.1028 e_{t-1}^2$</td>
</tr>
<tr>
<td></td>
<td>MAPE</td>
<td>0.38 %</td>
</tr>
<tr>
<td><strong>ARI(100)-ARCH(1).M</strong></td>
<td>Volatility does not explain the variable in level: $t_s = 0.93$</td>
<td>0.38 %</td>
</tr>
<tr>
<td><strong>ARI(100)-EARCH(1).M</strong></td>
<td>$Y_t = 0.167 Y_{t-1} + 0.041 Y_{t-15} + 0.043 Y_{t-50} + 0.038 Y_{t-65} - 0.059 Y_{t-66} + 0.049 Y_{t-77} - 0.072 Y_{t-86} + 0.066 Y_{t-87}$</td>
<td>0.38 %</td>
</tr>
<tr>
<td>without asymmetry</td>
<td>$-0.036 Y_{t-95} + 0.062 Y_{t-100} + 0.194 \sqrt{h_t}$</td>
<td>$= -10.047 + 0.186 \frac{e_{t-1}}{\sqrt{h_{t-1}}}$</td>
</tr>
<tr>
<td></td>
<td>$ln(h_t) = -10.047 + 0.186 \frac{e_{t-1}}{\sqrt{h_{t-1}}}$</td>
<td>$= -10.047 + 0.186 \frac{e_{t-1}}{\sqrt{h_{t-1}}}$</td>
</tr>
<tr>
<td></td>
<td>MAPE</td>
<td>0.38 %</td>
</tr>
<tr>
<td><strong>ARI(100)-EARCH(1).M with asymmetry</strong></td>
<td>$Y_t = 0.167 Y_{t-1} + 0.041 Y_{t-15} + 0.042 Y_{t-50} + 0.038 Y_{t-65} - 0.058 Y_{t-66} + 0.049 Y_{t-77} - 0.072 Y_{t-86} + 0.066 Y_{t-87}$</td>
<td>0.38 %</td>
</tr>
<tr>
<td></td>
<td>$-0.036 Y_{t-95} + 0.061 Y_{t-100} + 0.02 \sqrt{h_t}$</td>
<td>$= -10.05 + 0.186 \frac{e_{t-1}}{\sqrt{h_{t-1}}} + 0.00129 \frac{e_{t-1}}{\sqrt{h_{t-1}}}$</td>
</tr>
<tr>
<td></td>
<td>$ln(h_t) = -10.05 + 0.186 \frac{e_{t-1}}{\sqrt{h_{t-1}}} + 0.00129 \frac{e_{t-1}}{\sqrt{h_{t-1}}}$</td>
<td>$= -10.05 + 0.186 \frac{e_{t-1}}{\sqrt{h_{t-1}}} + 0.00129 \frac{e_{t-1}}{\sqrt{h_{t-1}}}$</td>
</tr>
<tr>
<td></td>
<td>MAPE</td>
<td>0.38 %</td>
</tr>
<tr>
<td><strong>ARI(100)-GJR-EARCH(1) with asymmetry</strong></td>
<td>$Y_t = 0.161 Y_{t-1} + 0.039 Y_{t-15} + 0.042 Y_{t-50} + 0.042 Y_{t-65} - 0.054 Y_{t-66} + 0.05 Y_{t-77} - 0.069 Y_{t-86} + 0.065 Y_{t-87}$</td>
<td>0.38 %</td>
</tr>
<tr>
<td></td>
<td>$-0.033 Y_{t-95} + 0.063 Y_{t-100}$</td>
<td>$= 0.000045 + 0.1104 e_{t-1}^2 - 0.013 e_{t-1}^2 I(e_{t-1} &lt; 0)$</td>
</tr>
<tr>
<td></td>
<td>$h_t = 0.000045 + 0.1104 e_{t-1}^2 - 0.013 e_{t-1}^2 I(e_{t-1} &lt; 0)$</td>
<td>$= 0.000045 + 0.1104 e_{t-1}^2 - 0.013 e_{t-1}^2 I(e_{t-1} &lt; 0)$</td>
</tr>
</tbody>
</table>
Step 2: One estimates the eventual long-run equilibrium relationship among the different variables of the systems and one covers the residues $RES_t$ of this equation. This error term represents the disequilibrium or cointegrating regression. The stationarity of $RES_t$ residues implies that the variables are cointegrated, and in order to test the stationarity of $RES_t$, the appropriate ADF equation are used. Indeed, the residuals have a mean of zero and hence it is not necessary to inspect the presence of a linear trend. One may also use the usual statistical Durbin and Watson (DW) under certain conditions (Mourad, 2007). To test the existence of a unit root in the residuals $RES_t$ associated to the static relationship, one proceeds as follows:

$$RES_t = \theta_0 + \sum_{i=1}^{m+1} \theta_i RES_{t-i} + u_t \quad (E)$$

$$\Delta RES_t = \theta RES_{t-1} + \sum_{i=1}^{m} \theta_i \Delta RES_{t-1} + u_t \quad (E)$$

It is worth mentioning here that the order $m$ is determined by using the Ljung-Box Q-statistic for the residuals of the model (M). In the present case, for each system, each component is I(1) and consequently all variables are integrated at the same order. Using the data file (F2) of size 2800, one tests whether the disequilibrium error $RES_t$ is I(0). For this, $t_B$ is compared to critical value for a 5% level of significance tabulated by Mackinnon (1991). The results of the testing for the long-run relationships are given in Table (4). For all systems, the cointegrating regression is accepted. Therefore, a variation in the dependent variable (per example, $High_t$ in system 1, $Low_t$ in system 2) depends on the variation in the variable $Open_t$, where the different lags are given in Table (5) and in the magnitude of the departure from the long-run relationship at the previous period. The negative coefficients of $ECT_{t-1}$, -0.3339, -0.4125, -0.2098 and -0.0999 respectively in the systems 1, 2, 3 and 4, represent the adjustment speed that leads to validate the ECM model and there will be a return of the dependent variable to its equilibrium in the long-run. Finally, the ECM for all systems is estimated. In Table (5), one deals only with the lagged corresponding parameters, which are significantly different from zero.

For each system, a prediction step by step (ex-post forecasts) covering the period from September 24, 2011 until March 01, 2013, that is 373 days is performed. The forecasting performance is measured by the MAPE criterion (see Table 5). The inspection of the results reveals the importance of the proposed models especially for the first two systems 1 and 2. Indeed, the value of MAPE is 0.3%, an excellent result was found among all models. These results are of great interest to measure risk in the exchange rate EUR / USD. Therefore, if a shock in the high, for example, produces a deviation from the target balance, a restoring force of 33.39% will be generated to correct it the next day. This deviation, within three days, the variable High returns to its long-term target. The same conclusion goes for the variable Low, but with faster restoring force (41.25%). The advice could be granted to persons interested in the exchange rate EUR / USD because it accentuates the confidence of the speculators of the stock market in this efficient forecasting results.
<table>
<thead>
<tr>
<th>Systems</th>
<th>$q$</th>
<th>$t_{\bar{q}}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$m=2$</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
| $X_t = \text{Open}_t Y_t = \text{Low}_t$ | $Y_t = 0.995 \times X_t$  
(12004.8)  
$R^2 = 99.91\%$  
$DW=1.71$ | 24  | -5.32       |
|                              | The intercept is not significantly different from zero |
| $m=2$                        |     |              |
| $X_t = \text{Open}_t Y_t = \text{High}_t$ | $Y_t = 0.00175 + 1.00364 X_t$  
(2.51)  
(1802.89)  
$R^2 = 99.91\%$  
$DW=1.82$ | 24  | -5.82       |
| $m=3$                        |     |              |
| $X_t = \text{Open}_t Y_t = \text{Low}_t$ | $Z_t = 0.0018 + 0.6341 X_t + 0.3713 Y_t$  
(2.8)  
(36.32)  
(21.18)  
$R^2 = 99.92\%$  
$DW=1.5$ | 28  | -3.65       |
| $Z_t = \text{High}_t$       |     |              |
| $m=4$                        |     |              |
| $X_t = \text{Open}_t Y_t = \text{Low}_t$ | $W_t = 0.7569 X_t - 0.5020 Y_t + 0.7475 Z_t$  
(68.82)  
(-29.48)  
(66.76)  
$R^2 = 99.97\%$  
$DW=1.77$ | 28  | -4.98       |
| $Z_t = \text{Close}_t$      |     |              |
| $W_t = \text{High}_t$       |     |              |
|                             | The intercept is not significantly different from zero |

The critical values of 5% level of significance are: $m=2$, -3.33; $m=3$, -3.74; $m=4$, -4.10

Source: Based on MacKinnon (1991)
The test is significant at 10% level. The critical value is -3.45
### TABLE 5

The Estimate Error Correction Models and Forecasts

<table>
<thead>
<tr>
<th>Variable $\Delta Y_t$</th>
<th>System $: X_t = Open_t, Y_t = Low_t$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$Q(50) = 55.41$</td>
</tr>
<tr>
<td></td>
<td>Q represents the Ljung-Box statistics</td>
</tr>
<tr>
<td>$ECT_{t-1}$</td>
<td>MAPE</td>
</tr>
</tbody>
</table>

| Lags of $\Delta X_t$  | 1 2 3 4 6 20 29 55 56 63 71 73 76 77 80 85 92 101 114 |
| Lags of $\Delta Y_t$  | 123 10 13 17 21 41 47 52 58 96 131 139 164 194 222 |

<table>
<thead>
<tr>
<th>Variable $\Delta Z_t$</th>
<th>System $: X_t = Open_t, Y_t = Low_t, Z_t = High_t$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$Q(50) = 57.46$</td>
</tr>
<tr>
<td>$ECT_{t-1}$</td>
<td>MAPE</td>
</tr>
</tbody>
</table>

Note: $MAPE = 0.30\%$
<table>
<thead>
<tr>
<th>Variable $\Delta W_t$</th>
<th>$X_t = \text{Open}_t$, $Y_t = \text{Low}_t$, $Z_t = \text{Close}_t$, $W_t = \text{High}_t$</th>
<th>$ECT_{t-1}$</th>
<th>MAPE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lags of $\Delta X_t$</td>
<td>0 1 2 3 6 10 29 32 43 55 56 71 76 84 94 101 114 116 131 151 194 204 207 225 331 345</td>
<td>-0.298 (-9.79)</td>
<td>0.38 %</td>
</tr>
<tr>
<td>Lags of $\Delta Y_t$</td>
<td>4 20 46 52 64 77 85 92 105 117 187 196 239 263 279</td>
<td>-0.099 (-1.9)</td>
<td>0.42 %</td>
</tr>
<tr>
<td>Lags of $\Delta Z_t$</td>
<td>1 2 3 7 10 17 20 21 30 32 41 58 96 186 204 222 223 227 259 307 324 366 371</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Lags of $\Delta W_t$</td>
<td>25 111 116 128 139 201 259 324 394</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
CONCLUSION

In this paper, 4 main points will be beneficial for those who supervise the evolution of the exchange rate EUR / USD. The first point shows that the alternation of High and Low on the market follows a uniform distribution and hence if someone bets on this alternation then he puts himself in a position of maximum uncertainty. The second point is related to the daily volatility of High and Low. These variables require a first difference to become stationary and the residuals associated to the integrated autoregressive models have an ARCH effect. The five proposed models associated to the variables in first differences and volatility have the same predictive performance (MAPE = 0.38%). It seems that the statistical quality of the models AR(81).M-EARCH (1) without asymmetry and ARI (81).M-EARCH (1) is better for High variable, while for the variable Low, ARI (100)-ARCH (1) and ARI (100)-EARCH (1).M without asymmetry seem the best models. The latter point seems the more interesting one. In fact, the components of each of the four systems are cointegrated. More precisely, the components of each system (High, Open) and (Low, Open) are linked by a long-run equilibrium relationship. In addition, the error correction mechanism is very fast, 33.39% for the Low variable and 41.25 % for the High variable. Also, a return to equilibrium occurs between two and three days, and the short-term forecasts for High and Low variables are very close to the reality (MAPE = 0.3%). As a conclusion, the (ECM) models led to a 21% improvement in prediction accuracy when compared to the ARI-ARCH models.

RECOMMENDATIONS

At the end of this research, a large question arises: can one determine the probability of the predicted values of the two variables High and Low? These probabilities could be empirically estimated using the proposed models for each of the two variables provided if the parameters stability is validated by an adequate test as the Chow test for parameter stability or the recursive Chow test.

REFERENCES


